









Defining TSM&O – MAP-21

- Not just ITS
- MAP-21 revised federal definition of TSM&O (23 U.S.C. § 101(a)(30))
 - Integrated strategies to optimize existing infrastructure performance
 - Multimodal and intermodal, cross-jurisdictional systems, services, and projects
 - Preserve capacity and improve security, safety, and reliability of transportation system
 - Includes coordinated regional implementation and interoperability
- WisDOT TSM&O State of the State Report adopts MAP-21 definition adding:
 - "Plans to retire system components that no longer provide sufficient benefit to warrant continuation or are technologically obsolete."



Example TSM&O Traffic Infrastructure Strategies

- Work Zone Management
- Traffic Incident Management
- Service Patrols
- Special Event Management
- Road Weather Management
- Transit Management

- Traffic Signal Coordination
- Surveillance and Monitoring
- Traveler Information
- Ramp Management
- Managed Lanes
- Active Traffic Management
- Integrated Corridor Management
- Truck Parking

TSM&O History at WisDOT Early ITS Infrastructure

- Ramp Metering
 - Began in 1969 in Milwaukee
- Other infrastructure
 - Loop detectors 70s
 - Dynamic message signs (DMS) 90s
- Legacy Problems
 - No "pavement equivalent" method of considering traffic operations and management infrastructure
 - ITS deployments sporadic
 - Legislative issues No direct ITS funding

Advancing TSM&O Infrastructure Deployments

- "Low hanging fruit" addressed where to go next?
- Previous deployments based on old data
- New technologies maturing rapidly
 - Connected vehicle infrastructure
 - Probe-based traffic data
 - In-car travel time displays
 - Multipurpose cameras
 - Smart traffic signals
- System needs to be more flexible to adapt quickly







- Program Development Refinements
- Needs Analysis Tool Refinements
- Benefits Tool Refinements
- TSMO-TIP March Webinar
- Regional Workshops
- Annual Report will be available on TSMO-TIP website



TSMO-TIP Objectives

- Develop a traffic infrastructure deployment process focused on:
 - Continuous performance improvement
 - Annual process open to technological advances
 - Current and short-term needs
 - Needs analysis tool to identify system issues
 - Decision making support
 - Process checklist and benefits analysis tool
 - Process documentation
 - Project justification and historical reference
- Support federal requirements

TSMO-TIP Expectations

What it is...

- Provides a defined, consistent process methodology
- High level evaluation using historical data and numbers
- Needs data identifies general areas of concern
- Benefits analysis estimates potential project benefits
- Documents project information, data and decisions
- And what it isn't...
 - Does not provide a "go or no go" decision
 - Does not identify deployment solutions

























What data does the user need to obtain to calculate benefits?















FY17 Standalone Approved Projects ITS Projects needing TSMO-TIP Documentation

- Bureau of Traffic Operations
 - BTO: I43 Locust DMS Replacement
- Northeast Region
 - NE002: Leo Frigo Bridge Security
 - NE003: Northeast Region CCTV's
- Northwest Region
 - NW002(FY16): USH 53 Eau Claire Freeway TOIP Implementation South
 - NW005: City of Eau Claire, USH 12, ITS Install
 - NW007: Portable Camera Trailer



FY17 Standalone Approved Projects ITS Projects needing TSMO-TIP Documentation

- North Central Region
 - N/A
- Southwest Region
 - SW002: IH 90/94 Tomah to Wis. Dells, ITS Enhancement
 - SW007: USH 151, American Parkway Interchange, Madison, ITS Enhancement
 - SW008: USH 12, Middleton, ITS Enhancement
- Southeast Region
 - SE002: Communication Construction 164 & 190
 - SE008: Communication Design of STH 20 & STH 31













Emerging Technologies

- Traveler Information / RTSMIP
- Communications Systems / Connectivity
- Adaptive Signal Control
- Active Traffic Management
- Detection Systems
- Probe Data
- Big Data
- Connected Vehicles
- Automation
- Other high-tech TSM&O
- Emerging low-tech TSM&O









- States preparing networks for CV
- Adding redundant/dedicated lines
- What to do in rural areas?
 - Fiber, Wireless, Leased (cellular)?
- Local Example
 MinDOT fiber undete Dep 1
 - WisDOT fiber update Don Schell





Adaptive Signal Control – Many Different Systems

- SCOOT (Split Cycle Offset Optimization Technique)
- SCATS (Sydney Coordinated Adaptive Traffic System)
- LA ATCS (LA DOT Adaptive Traffic Control System)
- RHODES (Real Time Hierarchical Optimized Distributed Effective System)
- ACS-Lite (Econolite Centracs is advanced version)
- OPAC (Optimization Policies for Adaptive Control)
- InSync (Rhythm Engineering)
- ATMS.now (formerly Streetwise, by Naztec)
- RTACL (Real Time Adaptive Control Logic)
- QuicTrac Adaptive (by McCain)
- SPOT (Omaha, Nebraska)









Detection Systems – Overview

- Real-time monitoring
- Intersection actuation
- Traffic data collection
- Automated incident detection
- Thermal detection
- Origin/Destination detection



Intersection performance management











Big Data – Trends

- Information sharing across departments and systems
- Predicting traffic jams up to an hour in advance
- Optimize freight movements and routing
- Real-time traffic monitoring and control
- Local Example Peter Rafferty
 - Planning for ATMS/CV data
 - WisTransPortal and TSM&O DSS
 - Driving simulator data



Connected Vehicles – Overview

- Vehicle-to-Vehicle (V2V)
- Vehicle-to-Infrastructure (V2I)
- Vehicle-to-Anything (V2X)
 - Pedestrians

- Bicycles / mopeds
- Connected everything Internet of Things
- Communications standards
 - Dedicated short-range communications (DSRC) radios
 - Wireless/cellular technologies including 5G



Connecte	d Vehicle Ap	plications			
V2I Safety Red Light Violation Warning	Environment Eco-Approach and Departure at	Mobility Advanced Traveler Information System			
Curve speed warning Stop Sign Cap Assist Spot Weather Impact Warning Reduced Speed/Work Zone Warning Pedestrian in Signalized Crosswalk Warning (Transit)	Contraction in the section of the se	(I-SIG) Signal Priority (transit, freight) Mobile Accessible Pedestrian Signal System (PED-SIG) Emergency Vehicle Preemption (PREEMPT) Dynamic Speed Harmonization (SPD-HARM) Queue Warning (Q-V/ARN) Cooperative Adaptive Cruise Control (CACC) Incident Scene Pre-Arrival Staging Guidance for Emergency Responders (RESP-STG) Incident Scene Work Zone Alerts for Drivers and Workers (INC-ZONE)			
V2V Safety Emergency Electronic Brake Lights (EEBL) Forward Collision Warning (FCW) Intersection Movement Assist (IMA) Left Turn Assist (LTA)					
(BSWLCW) Do Not Pass Warning (DNPW) Vehicle Turning Right in Front of Bus Warning (Transit)	Dynamic Eco-Routing (light vehicle, transit, freight) Eco-ICM Decision Support System	(EVAC) Connection Protection (T-CONNECT) Dynamic Transit Operations (T-DISP) Dynamic Ridesharing (D-RIDE)			
Road Weather Motorist Advisories and Warnings (MAW) Enhanced MDSS Vehicle Data Translator (VDT) Weather Response Traffic Information (WxTINFO)	Probe-based Pavement Maintenance Probe-enabled Traffic Monitoring Vehicle Classification-based Traffic Studies CV-enabled Turning Movement & Intersection Analysis	Freight-Specific Dynamic Travel Planning and Performance Drayage Optimization Smart Roadside Wireless Inspection Smart Truck Parking Q U.S. Department of Transpor n 7			
Source: US DOT ITS JPO	CV-enabled Origin-Destination Studies				



Connected Vehicles – Trends

- V2I Deployment Coalition
 - Initiatives, Research, Partnerships, Guidance, StandardsSPaT Challenge
- CV Pilots Tampa, New York, Wyoming
- State Pilot Tests
 - Michigan MCity, Southeast Testbed
 - Arizona, California, Pennsylvania, Utah
- Standards CV Reference Implementation Architecture (CVRIA)
- Applications Open Source Application Development Portal (OSADP)
- Data Sharing Research Data Exchange (RDE)

Local Example

City of Madison CV Initiatives – Yang Tao

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Automation – Overview

- Autonomous vs. Automated
- Autonomed Vehicles on the road now
 - Google in Bay Area, Austin, Seattle, Phoenix
 - Uber/Volvo in Pittsburgh
 - Tesla's Autopilot
 - Ford
 - Testing in Michigan
 - Production by 2021

Autonomous Microtransit



n driver monito No Automation	tors the driving environment the full-time performance by the <i>human driver</i> of all aspects of the <i>dynamic driving task</i> , even when enhanced by warning or intervention systems	Human driver			
No Automation	the full-time performance by the <i>human driver</i> of all aspects of the <i>dynamic driving task</i> , even when enhanced by warning or intervention systems	Human driver			
		Thankarr arrest	Human driver	Human driver	n/a
Driver Assistance	the <i>driving mode</i> -specific execution by a driver assistance system of either steering or acceleration/deceleration using information about the driving environment and with the expectation that the <i>human driver</i> perform all remaining aspects of the <i>dynamic driving task</i>	Human driver and system	Human driver	Human driver	Some driving modes
Partial Automation	the <i>driving mode</i> -specific execution by one or more driver assistance systems of both steering and acceleration/ deceleration using information about the driving environment and with the expectation that the <i>human</i> <i>driver</i> perform all remaining aspects of the <i>dynamic driving</i> <i>task</i>	System	Human driver	Human driver	Some driving modes
Automated driving system ("system") monitors the driving environment					
Conditional Automation	the <i>driving mode-specific performance</i> by an <i>automated</i> <i>driving system</i> of all aspects of the dynamic driving task with the expectation that the <i>human driver</i> will respond appropriately to a <i>request to intervene</i>	System	System	Human driver	Some driving modes
High Automation	the <i>driving mode</i> -specific performance by an automated driving system of all aspects of the <i>dynamic driving task</i> , even if a <i>human driver</i> does not respond appropriately to a request to intervene	System	System	System	Some driving modes
Full Automation	the full-time performance by an automated driving system of all aspects of the dynamic driving task under all roadway and environmental conditions that can be managed by a human driver	System	System	System	All driving modes
24	Assistance Partial Automation ated driving Conditional Automation High Automation Full Automation	Assistance Information outcome of the dynamic driving task expectation that the human driver perform all remaining aspects of the dynamic driving task Partial the driving mode-specific execution by one or more driver assistance systems of both steering and acceleration/ deceleration using information about the driving environment and with the expectation that the human driver perform all remaining aspects of the dynamic driving task Automation the driving mode-specific performance by an automated driving task atted driving system ("system") monitors the driving environment the driving mode-specific performance by an automated driving system of all aspects of the dynamic driving task, with the expectation that the human driver will respond appropriately to a request to intervene High Automation the driving mode-specific performance by an automated driving system of all aspects of the dynamic driving task, even if a human driver does not respond appropriately to a request to intervene Full Automation the full-time performance by an automated driving task, even if a laspects of the dynamic driving task, even if a laspects of the dynamic driving task, even if a laspect to intervene Full Automation the full-time performance by an automated driving task under all readway and environmental conditions that can be managed by a human driver	Assistance Information control of units of the distance of the d	Assistance Interfactor location of the thread driving performality and the theta and system and system Termination of the thread driving task Partial the driving mode-specific execution by one or more driver assistance systems of both steering and acceleration/ deceleration using information about the driving environment and with the expectation that the human driver growth as the human driver of the dynamic driving task System Human driver Partial the driving mode-specific execution by one or more driver assistance systems of both steering and acceleration/ deceleration/ desceleration using information about the driving environment System Human driver Conditional the driving mode-specific performance by an automated driving task with the expectation that the human driver will respond appropriately to a request to intervene System System High the driving mode-specific performance by an automated driving task, even if a human driver does not respond appropriately to a request to intervene System System High the driving system of all aspects of the dynamic driving task, even if a human driver does not respond appropriately to a request to intervene System System High the full-time performance by an automated driving system of all aspects of the dynamic driving task, even if a laspects of the dynamic driving task under all roadway and environmental conditions that can be managed by a human driver System System System and envir	Assistance Indinator documentation activity perform all remaining aspects of the dynamic driving task and system Indinator documentation Partial Automation the driving mode-specific execution by one or more driver assistance systems of both seering and acceleration/ deceleration using information about the driving environment and with the expectation that the human driver perform all remaining aspects of the dynamic driving task System Human driver Human driver Automation the driving mode-specific performance by an automated driving task with the expectation that the human driver will respond appropriately to a request to intervene System System Human driver High Automation the driving mode-specific performance by an automated driving task with the expectation that the human driver will respond appropriately to a request to intervene System System Human driver High Automation the driving mode-specific performance by an automated driving system of all aspects of the dynamic driving task, even if a human driver does not respond appropriately to a request to intervene System System System System Full the full-time performance by an automated driving system of all aspects of the dynamic driving task, even if a laspects of the dynamic driving task under all roadway and environmental conditions that can be managed by a human driver System System System System Automation the full-time performance by an au

















Work Zone Queue Warning Systems (QWS)

- WisDOT has been looking for ways to decrease end-ofqueue crashes in work zones as well as provide more real-time traveler information to drivers in work zones
- Other states saw a safety benefit and reduced crashes with the QWS
- Wisconsin implemented a QWS in the Milwaukee and Madison area several years ago; however results were not well documented, and technology is getting cheaper and better



Federal Accelerated Innovation Deployment (AID) Grant

- WisDOT applied for a grant in December 2015 to fund two pilot QWS in the following locations:
 - I-39 near Stevens Point
 - I-39 Rock River Bridge near Edgerton (mega project)
- Grant was approved in May 2016
- As part of the grant, WisDOT will be submitting a detailed analysis and report to FHWA
- Currently developing QWS Decision Support Tool with UW TOPS Lab using data from automated TMP system
 - System will be used to help identify future projects to deploy QWS









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